

Combinatory Geometry

If ^{you are} ~~one is given~~ a theorem in geometry to prove, ^{you} one would usually first try to do it by discriptive methods, and if these failed, ^{you} one would have to resort to analytic methods.

The theorems to be considered in this lecture are all what may be called incidence theorems, i.e. if given that certain pts. lie on certain lines ~~and~~ ^{or} planes, to prove that a certain other pt. lies on a certain other line, line etc. The method about to be described, which considers how incidences must be combined to form a true theorem, enables one to obtain many such theorems by simple, almost mechanical, procedures.

We shall throughout use capital letters to represent points and small letters to represent lines if we are working in 2 dimensions and planes if we are working in 3 dimensions.

Take homog. co-ords x_1, x_2, x_3 in two dimensions.

The invariants may conveniently be written out in the form of a matrix, and to prove any geometrical theorem we have to show that if certain determinants of this matrix vanish, then a certain other determinant of the matrix also vanishes.

The application of this method is specially easy when all the conditions are the vanishing of determinants of the 2nd order. Simple example. Theorem of perspective Δ etc.

The process is quite straightforward but there is rather a lot of writing down.

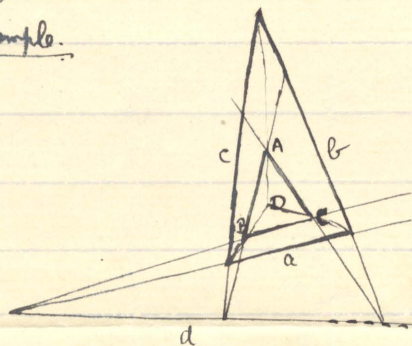
This may be avoided by the following method. Quadrangle method.

The quads may overlap.

So far we have used only determinants of the 2nd order. The algebra is not so simple when determinants of other orders are used, but the method can in this case be easily adapted to enable us to obtain one theorem from another. The procedure is like this.

The condition for an incidence of the r^{th} kind between r points and r hyps. is independent of n provided $n > r$. This holds for all proj. relations. We are, in fact, only interested in the sections of the hyps. with the space which is determined by the points: any other dimensions are irrelevant. We can therefore ^{let our small letters represent} use the idea of hyperplanes without stating the no. of dims. in which the hyperplanes lie, it being ^{understood} assumed that this no. is greater than the no. of dimensions determined by the points in which we are interested. A hyperplane in this sense is just something which meets any line in a point, any plane in a line, any V_3 in a V_2 etc.

Example.



$$\begin{vmatrix} Ba & Bc \\ Da & Dc \end{vmatrix} = 0$$

$$\frac{Ba \cdot Dc}{Bc \cdot Da} = 1$$

$$\frac{Cb \cdot Da}{Ca \cdot Db} = 1$$

$$\frac{Ad \cdot Bc}{Ac \cdot Bd} = 1$$

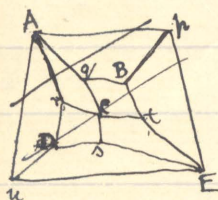
$$\frac{Bd \cdot Ca}{Ba \cdot Cd} = 1$$

$$\frac{Ad \cdot Bc}{Ac \cdot Bd} = 1$$

Multiplying we get $\frac{Cb \cdot Ad}{AB \cdot Cd} = 1$
 We have not used the fact that the 4 points are coplanar.
 In 3 dims. we get theorem of persp. tetrahedra.

General Theorem which can be stated entirely in terms of incidences of 2nd kind.

The incidences may be represented diagrammatically by $\rightarrow$



At the ends of each side of one of the quads. there

one of the letters represents a point, the other a hyp.

can be regarded as

of 2nd kind

Each quad. representing one incidence, the letters at its

elements

vertices representing the points taking part in the incidence.

The incidences are related in such a way that

If all the incidences except one are true the last one is also true, as can be seen from long fractions.

Each such diagram gives a theorem. The theorem will, of course, still be true if

(Part. base)

we make the elements satisfy any additional incidences. Suppose for simplicity that the

points all lie in 3 dimensions. We may regard the points as forming the vertices of a

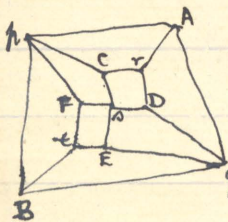
joining

represented by letters

polyhedron, the edges of the polyhedron being formed by each pair of points that are

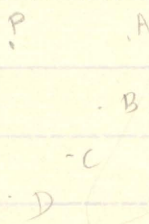
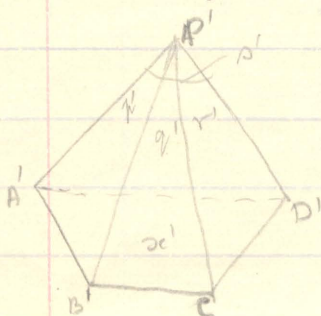
at opposite corners of a quad, and each face of the polyhedron containing all the points

that correspond to vertices joined to a given vertex (these points are assumed to be



coplanar when there are more than 3 of them). In a similar way

The theorem may be represented diagrammatically by a polyhedron, each vertex of the poly. cor. to a point, each face to a hyp. and each edge to the incidence of 2nd kind between the two points and ~~the~~ ^{the} hyp. which correspond to the two vertices at the end of the edge, and the two hyp. which correspond to the two faces bounded by the edge. ^{Prove that} If for any such polyhedron the incidences corresponding to all the edges except one are satisfied, the incidence corresponding to the remaining edge is satisfied. ^{Edge represents} ^{whose analytical} Line PA' gives the incidence which is rep.



condition is $\frac{P_p \cdot Aa}{P_o \cdot Ap} = 1$

Edge $P'B'$ gives $\frac{P_p \cdot Bp}{P_p \cdot Bq} = 1$

Edge $A'B'$ gives $\frac{Ap \cdot Bq}{Ap \cdot Bp} = 1$

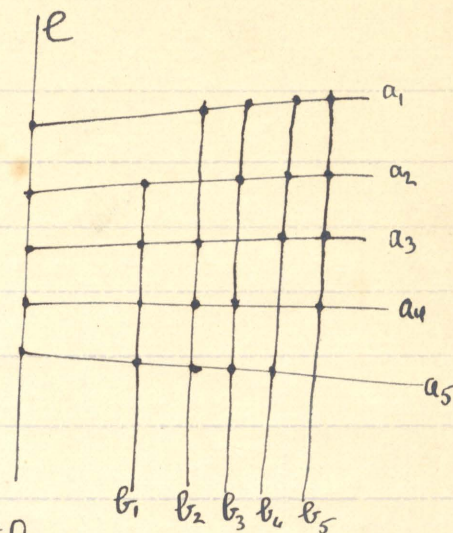
A special case of the foregoing is the theorem of perspective polyhedra, which states —

Line Geometry in 3 Dimensions

1. If co-ords of line a are $a_{12} a_{23} a_{31} a_{14} a_{24} a_{34}$
define $ab = a_{12} b_{34} + a_{23} b_{14} + a_{31} b_{24} + a_{14} b_{23} + a_{24} b_{31} + a_{34} b_{12}$
2. $ab = 0$ when lines a and b intersect. $aa = 0$ identically.
3. Each line occurs in one row and one column of the matrix.
4. Any projective relation between the lines is represented by an equation which is homogeneous in each line letter, and conversely.
meaning of vanishing of determinants
5. Any determinant of 7th order vanishes identically, but there is no other identity between the terms besides $aa = 0$.
6. A determinant of 6th order vanishes when ^{either or} the lines that form the rows or those that form the columns belong to a linear complex.
7. Determinant of 5th order formed by the lines with any other lines vanishes when the 5 lines have two common crossers. Consider $\begin{vmatrix} a & b & c & d & e & x & y \\ k_1 & k_2 & \text{any} & & & & \end{vmatrix}$ $\begin{vmatrix} a & b & c & d & e & x & y \\ \text{any 5 lines } k_1, k_2 & & & & & & \end{vmatrix}$ k_1, k_2 are crossers
8. Det. of 5th order formed by 5 lines with themselves consider $\begin{vmatrix} a & b & c & d & e & x & y \\ a & b & c & d & e & k_1 & k_2 \end{vmatrix}$
9. Prove converses of 7 and 8 by considering $\begin{vmatrix} a & b & c & d & e & k_1 & k_2 \\ a & b & c & d & e & k_1 & k_2 \end{vmatrix} + \begin{vmatrix} a & b & c & d & e & k_1 & y \\ a & b & c & d & e & x & k_2 \end{vmatrix}$ where k_1, k_2 meet abcd, 4th order det.
10. Det. formed by 4 lines with any other lines vanishes when the 4 lines lie on a quadric.
" " " " themselves vanishes when the lines have co-incident crossers.
Consider $\begin{vmatrix} a & b & c & d & k_1 & k_2 & k_3 \\ a & b & c & d & k_1 & k_2 & k_3 \end{vmatrix}$ where k_3 meets a b and c.
11. The lines $a_1, a_2, a_3, \dots$ are projectively related to the lines $b_1, b_2, b_3, \dots$ if
 $\frac{a_1 a_2 \dots a_n a_0}{a_1 a_2 \dots a_n a_0} = \frac{b_1 b_2 \dots b_n b_0}{b_1 b_2 \dots b_n b_0}$ etc. i.e. if $a_p a_q = f(p) f(q) b_p b_q$
(collineation)
 $a_p b_q = f'(p) f'(q) b_p a_q$
12. The projectivity is involuntary if

The Double Six.

$$b_1 \begin{vmatrix} b_1 & b_2 & a_1 & a_2 & a_3 & a_4 & a_5 \\ b_1 & 0 & . & 0 & 0 & 0 & 0 \\ b_2 & . & 0 & 0 & 0 & 0 & 0 \\ a_1 & 0 & 0 & & & & \\ a_2 & 0 & & 0 & & & \\ a_3 & 0 & 0 & & 0 & & \\ a_4 & 0 & 0 & & & 0 & \\ a_5 & 0 & 0 & & & & 0 \end{vmatrix} = 0$$



$$-2b_1b_2 \cdot b_1a_1 \cdot b_2a_2 \begin{vmatrix} a_3 & a_4 & a_5 \\ a_2 & a_3 & a_4 & a_5 \end{vmatrix} + (a_1b_1)^2 (a_2b_2)^2 \begin{vmatrix} a_3 & a_4 & a_5 \\ a_3 & a_4 & a_5 \end{vmatrix} = 0$$

$$b_1b_2 = \frac{a_1b_1 \cdot a_2b_2}{\begin{vmatrix} a_1 & a_3 & a_4 & a_5 \\ a_2 & a_3 & a_4 & a_5 \end{vmatrix}} \frac{\prod a_i a_k \cdot a_1 a_2}{\prod a_i a_k \prod a_2 a_k} = f(1)f(2) \cdot a_1 a_2 \quad \checkmark$$

$$b_1b_2 = a_1a_2 \cdot a_1b_1 \cdot a_2b_2$$

Any theorem concerning points and hyperplanes gives a theorem in algebra which states that if certain determinants of a matrix vanishes, then another determinant vanishes. If we now take a new set of points and hyperplanes, and form a new matrix in which each term is the s^{th} power of an invariant expression (Aa) , and apply the algebraic theorem to this matrix then a new geometric theorem will be obtained. A different theorem will be obtained for each different value of n . Most interesting are $s=2$ and $s=-1$.

Any relationship between certain elements will correspond to a different relationship between the corresponding elements for each different s .

$s=1$		$s=2$		$s=-1$	
$A_p=0$	A incident to p	$A'_p=0$	A' incident to p'	$A''_p=0$	must not occur
$\begin{vmatrix} A_p & A_q \\ B_p & B_q \end{vmatrix} = 0$	Incidence of 2 nd kind between AB & pq	$\begin{vmatrix} A_p^2 & A_q^2 \\ B_p^2 & B_q^2 \end{vmatrix} = 0$	same relation between $A'B'$ & $p'q'$	$\begin{vmatrix} \frac{1}{A_p} & \frac{1}{A_q} \\ \frac{1}{B_p} & \frac{1}{B_q} \end{vmatrix} = 0$	same
$\begin{vmatrix} A_p & A_q & A_r \\ B_p & B_q & B_r \\ C_p & C_q & C_r \end{vmatrix} = 0$	Incidence of 3 rd kind between ABC & pqr .	$\begin{vmatrix} A_p^2 & A_q^2 & A_r^2 \\ B_p^2 & B_q^2 & B_r^2 \\ C_p^2 & C_q^2 & C_r^2 \end{vmatrix} = 0$	(Take $p'q'r'$ as axes) $A'B'C'$ lie on a conic self polar to $p'q'r'$ (or dual relation)	$\begin{vmatrix} \frac{1}{A_p} & \frac{1}{A_q} & \frac{1}{A_r} \\ \frac{1}{B_p} & \frac{1}{B_q} & \frac{1}{B_r} \\ \frac{1}{C_p} & \frac{1}{C_q} & \frac{1}{C_r} \end{vmatrix} = 0$	$A'B'C'$ lie on a conic circumscribed to $p'q'r'$ (or dual)
$\begin{vmatrix} A_p & A_q & A_r & A_s \\ B_p & B_q & B_r & B_s \\ C_p & C_q & C_r & C_s \\ D_p & D_q & D_r & D_s \end{vmatrix} = 0$	Inc. of 4 th kind between $ABCD$ & $pqrst$	$\begin{vmatrix} A_p^2 & A_q^2 & A_r^2 & A_s^2 \\ B_p^2 & B_q^2 & B_r^2 & B_s^2 \\ C_p^2 & C_q^2 & C_r^2 & C_s^2 \\ D_p^2 & D_q^2 & D_r^2 & D_s^2 \end{vmatrix} = 0$	$A'B'C'D'$ lie on a quadric self polar to $p'q'r's'$	$\begin{vmatrix} \frac{1}{A_p} & \frac{1}{A_q} & \frac{1}{A_r} & \frac{1}{A_s} \\ \frac{1}{B_p} & \frac{1}{B_q} & \frac{1}{B_r} & \frac{1}{B_s} \\ \frac{1}{C_p} & \frac{1}{C_q} & \frac{1}{C_r} & \frac{1}{C_s} \\ \frac{1}{D_p} & \frac{1}{D_q} & \frac{1}{D_r} & \frac{1}{D_s} \end{vmatrix} = 0$	$A'B'C'D'$ lie on a cubic which passes through the edges of tet. $p'q'r's'$
		etc.			

Different results will be obtained by choosing different elements of the original theorem to represent the rows and columns of the matrix (it must of course, be possible to state all the incidences in the pqr theorem in terms of the elements chosen). Hence it is possible to obtain several different theorems from any given theorem for each value of s .

U Certain general methods can be obtained by this ^{is regarded as consisting entirely of relations}

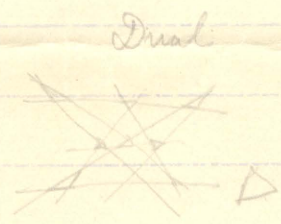
(17) Suppose ~~the~~ ^{all} the relations in the original theorem of a the type; - 3 points are collinear.

Then the matrix will be formed by all the points in the figure and 3 arbitrary hyps, and the analytical condition which expresses that 3 points are collinear will be the vanishing of the det.

^{having} with those three points as columns and the 3 arb. hyps. as rows. Then applying the ^{corresponding} method for $s=2$

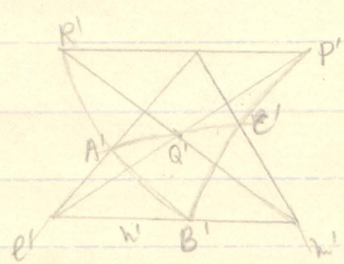
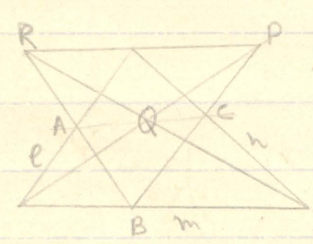
we find that the theorem will still be true when each straight line joining three points is replaced by a conic through the 3 points self conj. to the triangle formed by ^{any fixed} 3 lines.

Similarly for $s=1$ --- The points and conics need not be coplanar provided we replace the three ~~plan~~ sides of the triangle by 3 planes, and the conics are self conj. to the triangles formed by ^{the} their intersections of their planes with the 3 fixed planes.



If conics can be circumscribed to 8 of the little Δ 's and a fixed Δ , the a conic can be inscribed to 9th & the fixed Δ

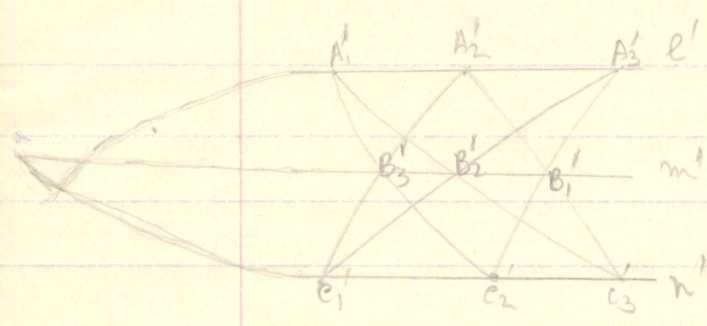
Other theorems obtained from Pappus' Theorem



Ad Bfm Cn
PQln' QR'mn' R'Pnl'
P'BC' Q'CA' R'AB'

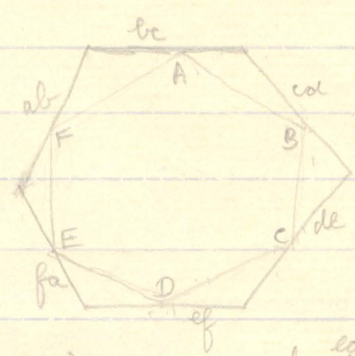
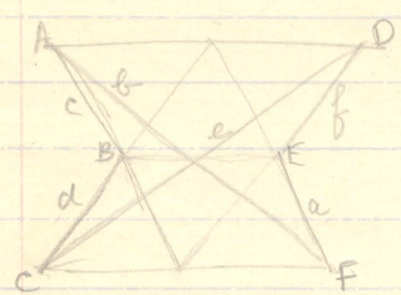
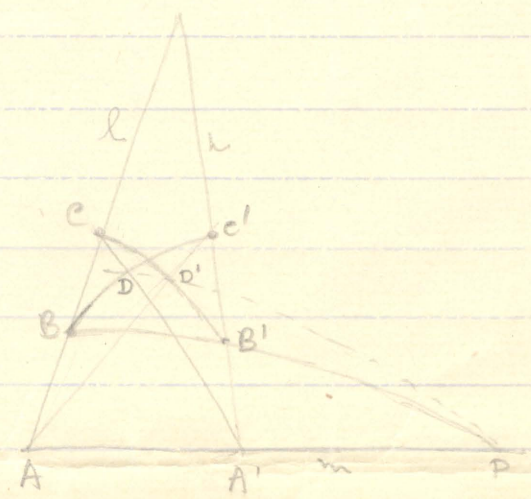
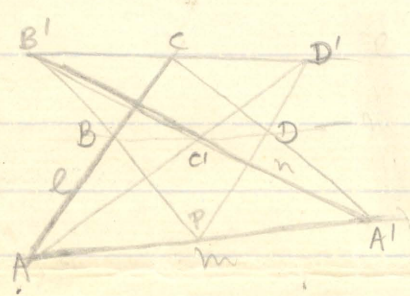
If we have two triangles one inscribed to the other, an 3rd Δ can be drawn ^{circumscribed} to ^(line) ^{PAR} ^{the 1st Δ inscribed to 2nd}, a 'conical Δ ' so ---

each side of the conical Δ being a conic self conj. to the 1st Δ



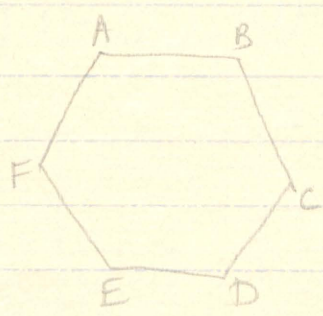
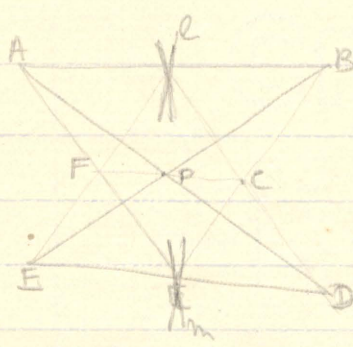
If sets of 3 points on two sides of a triangle are joined by ~~lines~~ conics self conj. to the Δ in such a way that the intersections of two pairs of conics lie on the 3rd side of Δ , then the intersection of the 3rd pair of conics also lies on this ^{side}

$A_1, A_2, A_3, B_1, B_2, B_3, C_1, C_2, C_3$
 $A_1B_3C_2, A_1B_2C_3$

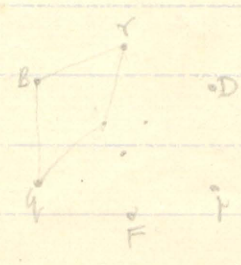
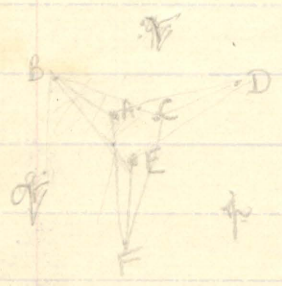
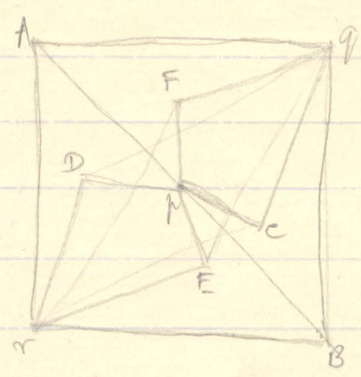
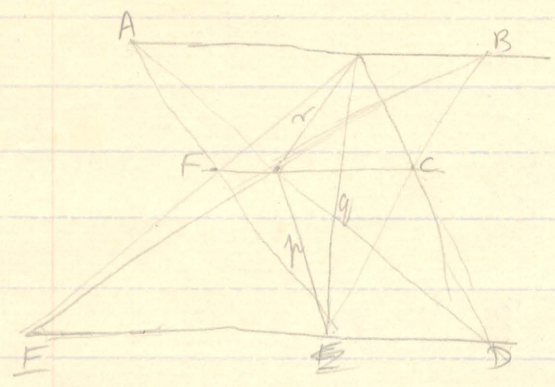


AD meets ad
 BE meets be
 CF " cf

If a skew hex^A in 5 dimension has its vertices on the ^{edge} faces of the dual of a skew hexagon^B, and corresponding diagonals of the two hexagons intersect. If ³ quadrics can be drawn touching the dual hexagon^B and self conj. to ³ of the tetrahedra formed by sets of 4 vertices of the ^{hex} ~~original~~ quad, the ^a quadrics can be drawn touching the dual hex. B and self conj. to any tetrahedron formed by 4 vertices of the hex A



We have ^{surface} a cubic ^{skew} passing through the edges of a Δ and a hexagon with its vertices on the cubic and each edge passing through one or other of two non-intersecting edges of the tetrahedron. If a point P is chosen such that conics can be drawn through P, A, D , and any 3 intersecting edges of the Δ , and conics can be drawn through P, B, E and Δ , then conics can be drawn through P, C, F and Δ .



$2\frac{1}{2}, 1\frac{1}{2}$

